

INSTRUMENT CATHODE-RAY TUBE

14 cm diagonal rectangular flat-faced oscilloscope tube with domed post-deflection acceleration mesh and metal-backed screen, primarily for use in compact oscilloscopes with 25 to 50 MHz bandwidth. This tube features a 1,5 W cathode with short warm-up time (quick-heating cathode).

QUICK REFERENCE DATA

Final accelerator voltage	$V_{g8(l)}$	10 kV
Display area		100 mm x 80 mm
Deflection coefficient		
horizontal	M_x	12,8 V/cm
vertical	M_y	6,3 V/cm

OPTICAL DATA

Screen		metal-backed phosphor
phosphor type		GH, colour green
persistence		medium short
Useful screen dimensions		≥ 100 mm x 80 mm
Useful scan		
horizontal	$\geq$	100 mm
vertical	$\geq$	80 mm
Spot eccentricity in horizontal and vertical directions	$\leq$	6,5 mm

HEATING

Indirect by AC or DC*		
Heater voltage	V_f	6,3 V
Heater current	I_f	0,24 A

* Not to be connected in series with other tubes.

MECHANICAL DATA**Mounting position**

The tube should not be supported by the base alone and under no circumstances should the socket be allowed to support the tube.

Net mass	approx. 1 kg
Base	14 pin, all glass
Final accelerator contact	small ball

Dimensions and connections

See also outline drawing

Overall length	≤	343 mm
Face dimensions	≤	100 x 120 mm ²

Accessories

Socket, supplied with tube	type 55566
Mu-metal shield	type 55592
Final accelerator contact connector	type 55569

FOCUSING

electrostatic

DEFLECTION

double electrostatic

x-plates

symmetrical

y-plates

symmetrical

Angle between x and y-traces

$90 \pm 1^\circ$

Angle between x-trace and horizontal axis of the face

≤ 5° *

If use is made of the full deflection capabilities of the tube the deflection plates will block part of the electron beam, hence a low impedance deflection plate drive is desirable.

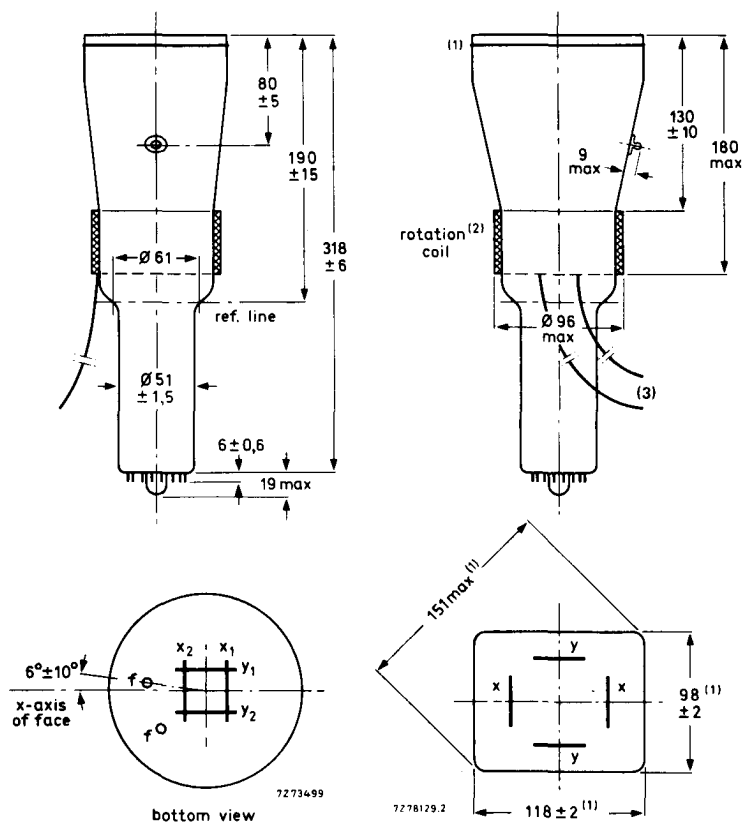
CAPACITANCES

x_1 to all other elements except x_2	$C_{x1(x2)}$	7 pF
x_2 to all other elements except x_1	$C_{x2(x1)}$	7 pF
y_1 to all other elements except y_2	$C_{y1(y2)}$	4 pF
y_2 to all other elements except y_1	$C_{y2(y1)}$	4 pF
x_1 to x_2	C_{x1x2}	2,2 pF
y_1 to y_2	C_{y1y2}	1,3 pF
Control grid to all other elements	C_{g1}	6 pF
Cathode to all other elements	C_k	2,7 pF

* The tube is provided with a rotation coil, concentrically wound around the tube neck, enabling the alignment of the x-trace with the mechanical x-axis of the screen. The coil has 1000 turns and a resistance of max. 350 Ω . Under typical operating conditions, max. 35 ampere-turns are required for the max. rotation of 5° . This means the required current is max. 35 mA at a required voltage of max. 12 V.

DIMENSIONS AND CONNECTIONS

Dimensions in mm



- (1) The bulge at the frit seal may increase the indicated maximum dimensions by not more than 2 mm.
 (2) The coil is fixed to the envelope by means of adhesive tape.
 (3) The length of the connecting leads of the rotation coil is min. 350 mm.

Fig. 1 Outlines.

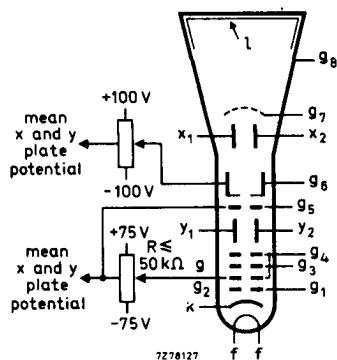


Fig. 2 Electrode configuration.

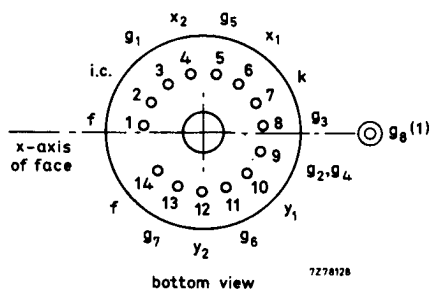


Fig. 3 Pin arrangement.

- (1) The centre of the contact is situated within a square of 10 mm x 10 mm around the true geometrical position.

TYPICAL OPERATION

Conditions

Final accelerator voltage	$V_{g8(l)}$	10 kV	
Post deflection accelerator mesh electrode voltage	V_{g7}	2000 V	
Geometry control electrode voltage	V_{g6}	2000 ± 100 V	see note 1
Interplate shield voltage	V_{g5}	2000 V	see note 2
First accelerator voltage	$V_{g2, g4}$	2000 V	
Astigmatism control electrode voltage	$\Delta V_{g2, g4}$	± 75 V	see note 3
Focusing electrode voltage	V_{g3}	400 to 560 V	
Cut-off voltage for visual extinction of focused spot	$-V_{g1}$	25 to 70 V	

Performance

Useful scan			
horizontal	$\geq$	100 mm	} see note 4
vertical	$\geq$	80 mm	
Deflection coefficient			
horizontal	M_x	12,8 V/cm	
		14 V/cm	
vertical	M_y	6,3 V/cm	
		7 V/cm	
Line width	l.w.	$\approx 0,38$ mm	see note 5
Deviation of deflection linearity		≤ 2 %	see note 6
Grid drive for 10 μ A screen current	V_d	≈ 20 V	
Geometry distortion	see note 7		

LIMITING VALUES (Absolute maximum rating system)

Final accelerator voltage	$V_{g8(l)}$	max.	12 kV
Post deflection accelerator mesh electrode voltage	V_{g7}	max.	2200 V
Geometry control electrode voltage	V_{g6}	max.	2200 V
Interplate shield voltage	V_{g5}	max.	2200 V
Accelerator voltage	$V_{g2, g4}$	max. min.	2200 V 1800 V
Focusing electrode voltage	V_{g3}	max.	2200 V
Control grid voltage	$-V_{g1}$	max. min.	200 V 0 V
Cathode to heater voltage			
positive	V_{kf}	max.	125 V
negative	$-V_{kf}$	max.	125 V
Grid drive, averaged over 1 ms	V_d	max.	20 V
Screen dissipation	W_{λ}	max.	8 mW/cm ²
Voltage between astigmatism control electrode and any deflection plate	$V_{g4/x}$ $V_{g4/y}$	max.	500 V 500 V
Control grid circuit resistance	R_{g1}	max.	1 M Ω

NOTES

1. The geometry control electrode voltage V_{g6} should be adjusted within the indicated range (values with respect to the mean x-plate potential).
2. The interplate shield voltage should be equal to the mean x-plate potential. The mean x-plate and y-plate potentials should be equal for optimum spot quality.
3. The astigmatism control electrode voltage should be adjusted for optimum spot shape. For any necessary adjustment its potential will be within the stated range.
4. The tube is designed for optimum performance when operating at a ratio $V_{g8(l)}/V_{g2}, g_4 = 5$.
If this ratio is smaller than 5, the useful scan may be smaller than 100 mm x 80 mm.
5. Measured with the shrinking raster method in the centre of the screen with corrections adjusted for optimum spot size, at a beam current of 10 μA .
6. The sensitivity at a deflection of less than 75% of the useful scan will not differ from the sensitivity at a deflection of 25% of the useful scan by more than the indicated value.
7. A graticule consisting of concentric rectangles of 95 mm x 75 mm and 93 mm x 73 mm is aligned with the electrical x-axis of the tube. With optimum corrections applied, the edges of a raster will fall between these rectangles.